

**A CARRIER FOR HOLDING A FLEXIBLE FLUID  
PROCESSING CONTAINER**

**Field of the Invention**

The invention relates to blood processing  
5 systems and apparatus.

**Background of the Invention**

Today, people routinely separate whole  
blood by centrifugation into its various  
therapeutic components, such as red blood cells,  
10 platelets, and plasma.

Conventional blood processing methods use  
durable centrifuge equipment in association with  
single use, sterile processing systems, typically  
made of plastic. The operator loads the  
15 disposable systems upon the centrifuge before  
processing and removes them afterwards.

The centrifuge chamber of many  
conventional centrifuges takes the form of a  
relatively narrow arcuate slot or channel. Loading  
20 a flexible processing container inside the slot  
prior to use, and unloading the container from the  
slot after use, can often be time consuming and  
tedious.

**Summary of the Invention**

25 The invention makes possible improved  
liquid processing systems that provide easy  
loading and unloading of disposable processing  
components. The invention achieves this objective  
without complicating or significantly increasing  
30 the cost of the disposable components. The

invention allows relatively inexpensive and straightforward disposable components to be used.

The invention provides a processing assembly for insertion into and removal from a channel which, in use, is rotated to create a centrifugal field. The processing assembly comprises a generally flexible processing container and a carrier, to which the processing container is attached. The carrier shapes the processing container to generally match the configuration of the channel. The carrier limits deformation of the processing container during its insertion into and removal from the channel. Inside the channel, the processing container receives fluids, e.g., blood, for separation in the centrifugal field.

The features and advantages of the invention will become apparent from the following description, the drawings, and the claims.

**Brief Description of the Drawings**

Fig. 1 is a side view, partly in section, of a centrifuge having a channel into which a flexible processing container carried by a generally stiff carrier have been inserted for use, the centrifuge being shown in an operational condition;

Fig. 2 is a side view of the centrifuge shown in Fig. 1, also partly in section, having been rotated by about 90° to reveal other structural features not shown in Fig. 1;

Fig. 3 is a side view, partly in section, of the centrifuge shown in Fig. 1, except that the channel has been swung upward to receive the flexible processing container and carrier as a unit;

Fig. 4 is a front plan view of the flexible processing container shown in Fig. 1;

5 Fig. 5 is a schematic, perspective view of the interior of the processing container shown in Fig. 4, showing details of the separation of whole blood into red blood cells and platelet-rich plasma in the whole blood entry region of the container;

10 Fig. 6 is a top sectional view of the processing container shown in Fig. 4, showing various contours formed along the high-G and low-G sides of the separation zone to enhance centrifugal separation of blood;

15 Figs. 7 and 8 are perspective views, taken along the low-G side of the channel, showing further details of one of the contours shown in Fig. 6, which comprises an inclined ramp used to help govern the collection of platelet-rich plasma from the container;

20 Fig. 9 is a schematic view of the separation of blood within the processing container shown in Fig. 4, showing the dynamic flow conditions which the various contours shown in Fig. 6 develop.

25 Fig. 10 is a plan view of the processing container shown in Fig. 4 with an integrally attached, multiple lumen umbilicus to conduct fluids to and from the container in a seal less system;

30 Fig. 11 is a section view of the umbilicus taken generally along line 11-11 in Fig. 10;

35 Fig. 12A is a perspective, exploded view of the processing container and a generally stiff carrier, which aids its insertion into and removal

from the channel of the centrifuge shown in Fig. 1;

Fig. 12B is a perspective, assembled view of the processing container and carrier shown in Fig. 12A;

Fig. 13 and 14 are perspective views of a processing container shown in Fig. 4 when carried by a generally stiff carrier, which can be placed in a generally lay-flat condition for storage (Fig. 13) and rolled into a curved condition for insertion into the channel (Fig. 14);

Fig. 15 is a perspective view of a slotted carrier, which carries a processing container shown in Fig. 4, to aid in its insertion into and removal from the channel of the centrifuge shown in Fig. 1;

Fig. 16 is a perspective view of a tool intended to be fitted over the top of a processing container, as shown in Fig. 4, to aid its insertion into and removal from the channel of the centrifuge shown in Fig. 1; and

Fig. 17 is a perspective view of the tool shown in Fig. 16, when fitted to the processing chamber for use in inserting and removing the chamber into and from the channel of the centrifuge shown in Fig. 1.

The invention may be embodied in several forms without departing from its spirit or essential characteristics. The scope of the invention is defined in the appended claims, rather than in the specific description preceding them. All embodiments that fall within the meaning and range of equivalency of the claims are therefore intended to be embraced by the claims.

**Description of the Preferred Embodiments**

Figs. 1 and 2 show a centrifugal processing system 10 that embodies the features of the invention. The system 10 can be used for processing various fluids. The system 10 is particularly well suited for processing whole blood and other suspensions of biological cellular materials. Accordingly, the illustrated embodiment shows the system 10 used for this purpose.

The system 10 includes a centrifuge assembly 12 and a fluid processing assembly 14, which is used in association with the centrifuge assembly 12, as Figs. 1 and 2 show. The centrifuge assembly 12 is intended to be a durable equipment item capable of long term use. The fluid processing assembly 14 is intended to be a single use, disposable item, which is loaded into the centrifuge assembly 12 at time of use and unloaded and discarded after use.

A stationary platform 16 carries the rotating components of the centrifuge assembly 12. The rotating components of the centrifuge assembly 12 include a yoke assembly 18 and a chamber assembly 20.

The yoke assembly 18 includes a yoke base 22, a pair of upstanding yoke arms 24 (best shown in Fig. 2), and a yoke bowl 26. The yoke base 22 is attached to a first axle 28, which spins on a bearing element 30 about the stationary platform 16. An electric drive 32, e.g., a permanent magnet, brushless DC motor, rotates the yoke assembly 18 on the first axle 28.

The chamber assembly 20 is attached to a second axle 34, which spins on a bearing element 36 within the yoke bowl 26. The yoke bowl 26 is

5 pivotally carried by pins 38 on the yoke arms 24. The yoke bowl 26 and, with it, the chamber assembly 20 it carries, swing as a unit on the pins 38 between a downward facing position for  
10 operation (shown in Figs. 1 and 2) and an upward facing position for loading the fluid processing assembly 14 (shown in Fig. 3). Fig. 3 shows the centrifuge assembly 12 before loading in the fluid processing assembly 14, whereas Figs. 1 and 2 show the centrifuge assembly 12 after loading in the fluid processing assembly 14.

15 A latch mechanism 40 releasably locks the yoke bowl 26 in the downward operating position. When the yoke bowl 26 is in the downward operating position, the axis of rotation 60 for the yoke assembly 18 (about axle 28) is generally aligned with the axis of rotation 62 of the chamber assembly 20 (about the axle 34).

20 The latch mechanism 40 can take various forms. In the illustrated embodiment (see Fig. 2), a pin 160 is carried by the yoke arm 24. The pin 160 is spring-biased to normally project into a key way 162 in the yoke bowl 26 when the yoke bowl 26 is located in its downward operating position.  
25 The interference between the pin 160 and the key way 162 retains the yoke bowl 26 in the downward position. The pin 160 includes a handle end 164, allowing the operator to manually pull the pin 160 outward, against its spring bias. This frees the pin 160 from the key way 162. With the pin 160 withdrawn, the operator can pivot the yoke bowl 26 into its upward facing position.  
30

35 The chamber assembly 20 includes an arcuate channel 42, which is defined between an outer wall 44, an inner wall 46, and a bottom wall

48. The channel 42 spins about the rotational axis 62. During rotation, the outer wall 44 becomes a high-G wall and the inner wall 46 becomes a low-G wall. The high-G wall and low-G wall together  
5 define the high and low limits of the centrifugal field.

The fluid processing assembly 14 includes a disposable processing container 64, which, in use, is carried within the channel 42 for common  
10 rotation, as Figs. 1 and 2 show. While rotating with the channel 42, fluids introduced into the container 64 separate as a result of centrifugal forces. Once the separation procedure is completed,  
15 the processing chamber 64 is intended to be removed from the channel 42 and disposed of.

The construction of the processing container 64 can vary, according to the separation objectives. In the illustrated embodiment, the container 64 is used to separate packed red blood  
20 cells (PRBC) and platelet-rich plasma (PRP) from whole blood (WB) drawn from a donor.

With this separation objective in mind (see Fig. 4), the processing container 64 comprises two elongated sheets 66A and 66B of a flexible, biocompatible plastic material, such as plasticized medical grade polyvinyl chloride, heat sealed together about their periphery. The fluid processing assembly 14 includes three tubing branches 68, 70, and 72 that communicate directly  
25 with the processing container 64. In the illustrated embodiment, the tubing branches 68, 70, and 72 are integrally connected to the processing container 64, so that the processing assembly 14 can be manufactured as a sterile,  
30 closed system.  
35

The first tubing branch 68 carries WB through an inlet port 74 into the container 64. The container 64 includes interior seals 76 and 78, which form a WB inlet passage 80 that leads 5 into a WB entry region 82. WB follows a circumferential flow path in the container 64, as it spins inside the channel 42 about the rotational axis 62. The side walls of the container 64 expand within the confines of the 10 channel ~~42~~ against the low-G wall 46 and high-G wall 44.

As Fig. 5 shows, WB separates in the centrifugal field within the container 64 into PRBC 84, which move toward the high-G wall 44, and 15 PRP 86, which are displaced by movement of the PRBC 84 toward the low-G wall 46. An intermediate layer 88, called the interface, forms between the PRBC 84 and PRP 86.

The second tubing branch 70 carries 20 separated PRP through a first outlet port 90 from the container 64. The interior seal 78 also creates a PRP collection region 92 in the container 64. The PRP collection region 92 is adjacent to the WB entry region 82. The velocity 25 at which the PRBC 84 settle toward the high-G wall 44 in response to centrifugal force is greatest in the WB entry region 82 than elsewhere in the container 64. There is also relatively more plasma volume to displace toward the low-G wall 46 in the 30 WB entry region 82. As a result, relatively large radial plasma velocities toward the low-G wall 46 occur in the WB entry region 82. These large radial velocities toward the low-G wall 46 elute 35 large numbers of platelets from the PRBC 84 into the close-by PRP collection region 92, for

collection through the second tubing branch 70.

The third tubing branch 72 carries separated PRBC 84 through a second outlet port 94 from the container 64. The interior seal ~~78~~<sup>16</sup> also forms a dog-leg 96 that defines a PRBC collection passage 98. A stepped-up barrier 100 (see Fig. 6) extends into the PRBC mass along the low-G wall 46, creating a restricted passage 102 between it and the facing high-G wall 44. The restricted passage 102 allows PRBC present along the high-G wall 44 to move beyond the barrier 100 into the PRBC collection passage 98 to the PRBC port 94. Simultaneously, the stepped-up barrier 100 blocks the passage of the PRP beyond it.

As Figs. 5, 7, and 8 show, the high-G wall 44 also projects toward the low-G wall 46 to form a tapered ramp 104 in the PRP collection region 92. The ramp 104 forms a constricted passage 106 along the low-G wall 46, along which the PRP 86 extends. The ramp 104 keeps the interface 88 and PRBC 84 away from the PRP collection port 90, while allowing PRP 86 to reach the PRP collection port 90.

In the illustrated embodiment (see Fig. 7), the ramp 104 is oriented at a non-parallel angle  $\alpha$  of less than  $45^\circ$  (and preferably about  $30^\circ$ ) with respect to the axis of the PRP port 90. The angle  $\alpha$  mediates spill-over of the interface 88 and PRBC 84 through the constricted passage 106.

As Figs. 7 and 8 show, the ramp 104 also displays the interface 88 for viewing through a side wall of the container 64 by an associated interface controller 108 (shown schematically in Fig 5). The interface controller 108 controls the relative flow rates of WB, PRP, and PRBC through

their respective ports 74, 90, and 94. In this way, the controller 108 maintains the interface 88 at a prescribed control location on ramp 104 close to the constricted passage 106 (as Fig. 7 shows),  
5 and not spaced away from the constricted passage 106 (as Fig. 8 shows). The controller 108 thereby controls the platelet content of the PRP collected through the port 90. The concentration of platelets in the plasma increases with proximity  
10 to the interface 88. By maintaining the interface 88 at a high position on the ramp 104 (as Fig. 7 shows), the plasma conveyed by the port 90 is platelet-rich.

Further details of a preferred embodiment  
15 for the interface controller are described in U.S. Patent 5,316,667, which is incorporated herein by reference.

As Fig. 5 and 6 show, radially opposed surfaces in the container 64 form a flow-restricting region 114 along the high-G wall 44 of the WB entry region 82. The region 114 restricts WB flow in the WB entry region 82 to a reduced passage, thereby causing more uniform perfusion of WB into the container 64 along the low-G wall 46.  
20 The constricted region 114 also brings WB into the entry region 82 at approximately the preferred, controlled height of the interface 88 on the ramp 104.  
25

As Fig. 6 shows, the low-G wall 46 tapers outward away from the axis of rotation 62 toward the high-G wall 44 in the direction of WB flow, while the facing high-G wall 44 retains a constant radius. The taper can be continuous (as Fig. 6 shows) or can occur in step fashion. These  
30 contours along the high-G and low-G walls 44 and  
35

46 produce a dynamic circumferential plasma flow condition generally transverse the centrifugal force field in the direction of the PRP collection region 92. As depicted schematically in Fig. 9,  
5 the circumferential plasma flow condition in this direction (arrows 214) continuously drags the interface 88 back toward the PRP collection region 92, where the higher radial plasma flow conditions already described exist to sweep even more  
10 platelets off the interface 88. Simultaneously, the counterflow patterns (arrow 216) serve to circulate the other heavier components of the interface 88 (the lymphocytes, monocytes, and granulocytes) back into the PRBC mass, away from  
15 the PRP stream.

As Fig. 10 best shows, the three tubing branches 68, 70, and 72 are coupled to an umbilicus 116. As Fig. 11 shows, the umbilicus 116 includes a coextruded main body 118 containing  
20 three interior lumens 120, which each communicates with one of the tubing branches 68, 70, and 72. The main body 118 is made, e.g., from HYTREL® 4056 Plastic Material (DuPont), which withstands high speed flexing.

25 As Fig. 10 shows, an upper support block 122 and a lower support block 124 are secured, respectively, to opposite ends of the umbilicus body 118. Each support block 122 and 124 is made, e.g., of a HYTREL® 8122 Plastic Material (DuPont),  
30 which are injection over-molded about the main umbilicus body 118. The over-molded blocks 122 and 124 include formed lumens, which communicate with the three umbilicus lumens 120. The three tubing branches 68, 70, and 72 (made from  
35 polyvinyl chloride material) are solvent bonded to

the ~~lower block~~ <sup>upper block</sup> 122 in communication with the umbilicus lumens 120. Additional tubing branches 126 (also made from polyvinyl chloride material) are solvent bonded to the ~~upper block~~ <sup>lower block</sup> 124 in communication with the umbilicus lumens 120. The additional tubing branches 126, in use, are placed in operative association with conventional peristaltic pumps, sensors, and clamps (not shown).

As further shown in Fig. 10, each support block 122 and 124 preferably includes an integral, shaped molded flange 128, to aid the installation of the umbilicus 116 on the centrifuge assembly 12, as will be described later. Each support block 122 and 124 further includes a tapered sleeve 130, which act as strain relief elements for the umbilicus 116 during use.

As Figs. 12A and 12B show, in the illustrated and preferred embodiment, the flexible processing container 64 is attached to a carrier 132. The carrier 132 possesses mechanical properties that limit deformation of the shape of the carrier 32 when subject to linear compression forces. The carrier 32 can be formed, e.g., from molded plastic, <sup>thermally formed material</sup>, vacuum-formed plastic, cardboard, or paper. The processing container 64 is secured to the carrier 132, e.g., by pinning, gluing, taping, or welding.

As Fig. 12B shows, the carrier 132 can be shaped to nest within the channel 64. The carrier provides an added degree of stiffness during handling to aid in the insertion of the processing container 64 into the channel 42, as well as the removal of the container 64 from the channel 42, without undue bending or shape deformation. The

carrier 132 can include a lubricious surface treatment, to further reduce interference and frictional forces during its insertion into and removal from the channel 42.

As Figs. 12 A and 12 B show, the material of the carrier 132 can be pre-shaped in a normally rounded, three-dimensional geometry, which nests within the interior of the channel 42. Alternatively (as Fig. 13 shows), the carrier 132 can, if made from semi-rigid material, be maintained before use in a generally lay-flat conditioned. At the time of use (see Fig. 14), the carrier 132 is rolled end-to-end and secured, e.g., using end tabs 134 fitting into end slots 135, to form the rounded, three-dimensional shape, which conveniently slides into the channel 42 in the manner shown in Fig. 12B. The carrier 132 can include spaced side tabs 136 to aid in grasping, lifting, and lowering the carrier 132 with respect to the channel 42.

As shown in Figs. 12A/B to 14, the carrier 132 extends along only one side of the container 64. Alternatively, as shown in Fig. 15, the carrier 132 can itself form a slotted structure, comprising a front wall 140 and a rear wall 142, forming a slot 144 between them. In this arrangement, the container 64 is sandwiched in the slot 144 between the front and rear walls 140 and 142.

As Fig. 15 shows, the carrier walls 140 and 142 can include preformed contoured surfaces, for example, surfaces 146, 148, 150, and 152. When filled with blood and undergoing centrifugation, the sides of the container 64 press against the surfaces 146 to 152. The contoured surfaces 146

to 152 of the carrier 132 define the high-G and low-G contours desired for the separation zone.

For example, a first contoured surface 146 projecting outward from the rear wall 142 can define the PRBC barrier 100. A second contoured surface 148 projecting from the front wall 140 can define the tapered ramp 104. Third and fourth contoured surfaces 150 and 152 projecting outward from the front and rear walls 140 and 142 can mutually press against and support the interior seal 78, to protect the seal 78 against failure or leakage. The other contours shown in Fig. 6, and more, can likewise be formed using the carrier 132.

Figs. 16 and 17 show another alternative embodiment of a carrier 166 for the flexible processing container 64. In this embodiment, the carrier 166 comprises a cap 168 having a top wall 170 and a depending side wall 172 shaped to nest within the channel <sup>42</sup>~~64~~. The side wall 172 possesses mechanical properties that limit its deformation when subject to linear compression forces. Like the carrier 32, the side wall 172 can be formed, e.g., from molded plastic, vacuum-formed plastic, cardboard, or paper.

The top wall 170 includes an interior groove 174, which receives the top edge 176 of the container 64. The groove 174 generally corresponds to the shape of the side wall 172. Together, the groove 174 and the side wall 172 shape the container 64 into the desired normally rounded, three-dimensional geometry for placement into the interior of the channel 42 (as Fig. 17 shows). A region 180 of the side wall 172 is cut away to accommodate passage of the tubes 68, 70, and 72

coupled to container 64.

The side wall 172 depends a distance from the top wall 170 sufficient to impart stiffness to the container 64 and thereby prevent buckling or undue bending or shape deformation of the container 64 when inserted into the channel 64. The cap 168 is intended to be removed once the container 64 has nested in the channel 64, and can thereafter be re-engaged when it is time to remove the container 64 from the channel 64. In the illustrated embodiment, the top wall 170 includes an exterior grip 178 for the operator to grasp (see Fig. 17), to further facilitate insertion and removal of the container 64 into and from the channel 42. The carrier 132 can include a lubricious surface treatment, to further reduce interference and frictional forces during its insertion into and removal from the channel 42.

The centrifuge assembly 14 includes upper and lower mounts 156 and 158. The mounts 156 and 158 receive the umbilicus support blocks 122 and 124, previously described. The mounts 156 and 158 hold the umbilicus 116 (see Figs. 1 and 2) in a predetermined orientation during use, which resembles an inverted question mark.

As Fig. 2 best shows, the upper umbilicus mount 156 is located at a non-rotating position above the chamber assembly 20, aligned with the rotational axis 62 of the assembly 20 when in its downward facing position. The lower umbilicus mount 158 is carried on the top of the chamber assembly 20, and is also aligned with the rotational axis 62. The lower umbilicus mount 158 is presented to the operator when the chamber assembly 20 is swung into its upward facing

orientation. Thus, with the chamber assembly 20 in its upward facing orientation (shown in Fig. 3), the carrier 132 (holding the container 64) can be conveniently loaded into the channel 42. The 5 umbilicus support block 122 can be loaded into the upper mount 156, just as the umbilicus support block 124 can be loaded into the exposed lower mount 158. The flanges 128 help orient the blocks 122 and 124 in their respective mounts 156 and 10 158.

When swung back into the downward facing orientation (see Fig. 2), the lower mount 158 holds the lower portion of the umbilicus 116 in a position aligned with the aligned rotational axes 15 60 and 62 of the yoke assembly 18 and chamber assembly 20. The mount 158 grips the lower umbilicus support 124 to rotate the chamber assembly 20 as the lower portion of the umbilicus 116 is rotated.

The upper mount 156 holds the upper portion of the umbilicus 116 in a non-rotating position above the yoke assembly 18. Rotation of the yoke base 22 brings a yoke arm 24 into contact with the umbilicus 116. This, in turn, imparts rotation to the umbilicus 116 about the rotational axis 60. Constrained by the upper mount 156, the umbilicus 116 also twists about its own axis 160 as it rotates. For every 180° of rotation of the first axle 28 about its axis 60 (thereby rotating the yoke assembly 180°), the umbilicus 116 will roll or twirl 180° about its axis 160. This 180° rolling component, when added to the 180° rotating component, cause the chamber assembly 20 to rotate 360° about its axis. The relative rotation of the 20 30 35 yoke assembly 18 at a one omega rotational speed

and the chamber assembly 20 at a two omega  
rotational speed, keeps the umbilicus 116  
untwisted, avoiding the need for rotating seals.  
The illustrated arrangement also allows a single  
5 drive element 32 to impart rotation, through the  
umbilicus 116, to the mutually rotating centrifuge  
elements 18 and 20. Further details of this  
arrangement are disclosed in Brown et al U.S.  
Patent 4,120,449, which is incorporated herein by  
10 reference.

Various features of the invention are set  
forth in the following claims.

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